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of the Mechanics of

Rigid Bodies ? The

forces act at

different points on

a rigid body but

but have the same
magnitude direction
and line of action
 $F_1 r_1 = F_2 r_2$ and? ? The
forces produce the
same moment about
any point and are
therefore
equipollent
external
forces' '*Vector*

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Introduction ?

Preceding chapters dealt with a determining external forces acting on a structure and b determining forces which hold together the various members of a structure ?

The current chapter
is concerned with
determining the
internal forces'

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Position Velocity

and Acceleration r ?

r ? Consider a

particle moving

along a certain

path ? Position
vector of a
particle at time t
is defined by a
vector between
origin O of a fixed
reference frame and
the position
occupied by
particle ? Consider
particle which

occupies'

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Introduction ? In preceding chapters it was assumed that surfaces in contact were either frictionless surfaces could move freely with respect to each other or rough tangential forces prevent

relative motion
between surfaces ?
Actually no
perfectly
frictionless
surface exists'

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